# Towards Self-Tracking Personal Pollution Exposure using Wearables

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## Outline

Introduction

Prototype

Calibration

Human Interference

Contributions

# Introduction

#### **Urban Pollution**

- Exposure to Urban Pollution is linked to many health risks particularly in older adults
- One of these risks is that Urban Pollution is positively associated with Mild Cognitive Impairment (MCI)

- Air Pollution: PM<sub>2.5</sub>
- Noise

# Mild Cognitive Impairment

- Precursor to Dementia
- It is estimated that 42.7 48.1 million people worldwide will have Dementia in 2020



#### Humans and Particulate Matter

- PM varies in size, shape, and chemical components
- Toxicity of PM differs with physical properties [Kelly and Fussell, 2012]
- Origin of suspended PM defines physical properties
- Outdoor-generated PM differs from Indoorgenerated PM
  - Outdoor: Traffic and Industrial activities
  - Indoor: Activities, human emissions, and some outdoor PM



### Personal Pollution Exposure

- Personal Cloud
  - Human emissions [Wallace et al., 2004]
  - Microenvironment emissions
- Personal Pollution Exposure is the amount of pollution inhaled
- Monitoring personal pollution exposure is key for health
  - Affected by humans-environment interactions
- Current solutions
  - Designed for quantified-selfers and scientists
  - Designed to be stationary



# My thesis work

Personal pollution exposure **prototype**  **Calibrating** lowcost PM<sub>2.5</sub> Sensors Study **human interference** with PM<sub>2.5</sub> Sensors

# Where did the **noise** go?

- Noise is a commonplace: extensively studied
- Microphone and smartphone microphone **calibration** [Zhu el al.,2015]
- Microphones are used for human activity recognition
  [Stork et. Al, 2012]
- Incorporated in **smart home** applications [Brdiczka et al.,2009]
- Development of **3D acoustic localization** technology [Haddad and Hald,2008]
- Microphones in passive Human-Robot interaction [Sekmen et al.,2002]



We focus on low-cost PM<sub>2.5</sub> sensors

Prototype

# Objectives



To create of a tool for older adults, and the general, to guide them to less polluted areas throughout their everyday activities

# Results: Wearable

- Personal Pollution Exposure Monitoring Tool
- Components
  - Low-cost off-shelf SoC: Raspberry Pi 3b+
  - Low-cost PM<sub>2.5</sub> Sensor: Plantower PMS7003
  - Off-the-shelf power bank
- Size and Weight most comfortable as handheld
- Functions with a companion smartphone application and a cloud database hosted on Amazon AWS



# Results: Smartphone Application

- Measures Noise in dBA using the built-in microphone
- Collects contextual data
  - Timestamps
  - Longitude and latitude
  - WiFi and GSM signal levels
  - Screen's brightness and illuminance values
  - Weather information
    - Outdoor temperature
    - Humidity
    - Dew point
    - Weather condition
    - Wind speed
  - Ambient temperature from battery temperature
  - Microenvironment and setting (manually input)





# Results: Ontology

- Personal Pollution Exposure Ontology
  - In OWL using Protege 5.5.0 build beta-3
  - Ontology describes personal pollution exposure events extensively
- API transforms raw sensor data from database to OWL individuals and attaches them to the ontology

# Mechanism



The wearable collects real-time PM2.5 data using the sensor and stores it locally



If WiFi is available, the wearable sends PM2.5 values to AWS cloud database



If WiFi is not available, the wearable connects with the smartphone via Bluetooth and sends the data to the smartphone. The smartphone sends the PM2.5 and the noise and contextual data to AWS database using GSM LTE



If Bluetooth is not available, wearable stores data locally until the next time it is connected



Ontology API pulls the data from the AWS database and attaches it to the ontology for further processing

# Challenges

Choosing the best sensor for the prototype (size and performance)

• Started with PMS5003 then upgraded to PMS7003

Sensor port is not a standard port

• Designed and soldered our own connectors

Raspberry Pi is not 100% reliable and might break

- Gone through multiple iterations for designing our own circuit board at UIC Makerspace and mHUB
- Still work in progress

#### myCityMeter Helping Older Adults Manage the Environmental Risk Factors for Cognitive Impairment

UIC HCI LAB University of Illinois, Chicago

# Calibration

# Objectives



Creating a model to rectify low-cost PM<sub>2.5</sub> sensors measurements



Understanding the effect of context on low-cost PM<sub>2.5</sub> sensors



- Used wearable with high-precision PM<sub>2.5</sub> monitoring tool: SidePak
- Collected data using the two meters at different contexts
- Classified the data and criteria-based subsets using three methods:
  - Naïve Bayes
  - Random Forest
  - Support Vector Machine

# Tools

- SidePak
  - Laser photometer to measure personal pollution exposure in real-time
- The Wearable
  - Plantower PMS7003 PM<sub>2.5</sub> Sensor
  - Laser scattering principle



# Data Collection

- SidePak and Wearable
- Pollutants: PM<sub>2.5</sub>, PM<sub>1</sub>, PM<sub>10</sub>, and, noise
- We collected data in different settings
  - Concentrations
  - Weather Conditions
  - Stationary and movement
  - Microenvironments
- Contextual data collected by smartphone app



#### The Data

- 70558 observations of 22 variables
- Approximately 20 hours
- 1 read/second



### Results

Classifier	Train	Test	Features	Accuracy
Naïve Bayes	28386	42172	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub>	71.10%
Random Forest	28431	42127	PM <sub>2.5</sub>	61.80%
Support Vector Machine	28431	28431	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub> Iuminosity, noise level, microenvironment, and, GSM signal strength	42%

#### Naïve Bayes

- Fairly Good Accuracy 71.1%
- Performed best with PM<sub>2.5</sub>, PM<sub>1</sub>, and, PM<sub>10</sub> as features

6 -	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
5-	0.0015	0.0010	0.0007	0.0440	0.8028	0.0000
liction - P	0.0033	0.0008	0.0692	0.3689	0.0282	0.0000
3- 3-	0.0031	0.1106	0.8638	0.5239	0.0282	0.1429
2-	0.0523	0.3206	0.0427	0.0335	0.0704	0.1429
1-	0.9397	0.5670	0.0236	0.0297	0.0704	0.7143
	1	2	3 Act	4 ual	5	6

#### Random Forest

- Accuracy 61.8%
- Performed better without any features: PM<sub>2.5</sub> only
- Data is biased toward groups with higher number of observations

6 -	0.0004	0.0003	0.0000	0.0000	0.0000	0.0000
5-	0.0030	0.0000	0.0000	0.0000	0.0000	0.0000
diction - 4	0.0388	0.0115	0.0005	0.0000	0.0000	0.0000
ق ط 3-	0.0090	0.0351	0.0044	0.0000	0.0000	0.0000
2-	0.2005	0.1085	0.2189	0.6686	0.0000	0.0000
1-	0.7482	0.8446	0.7762	0.3314	0.0000	0.0000
	1	2	3 Act	4 ual	5	6

#### Support Vector Machine

- Accuracy 42%
- Performed better with a large set of features: PM<sub>2.5</sub>, PM<sub>1</sub>, PM<sub>10</sub>, luminosity, noise level, microenvironment, and, GSM signal strength
- Data is biased toward groups with higher number of observations

6 -	0.0004	0.0004	0.0000	0.0000	0.0000	0.0000
5-	0.0018	0.0019	0.0013	0.0000	0.0208	0.0000
diction 4	0.0415	0.0433	0.0455	0.0399	0.0833	0.0000
а. З-	0.0728	0.0684	0.0750	0.0648	0.1250	0.0000
2-	0.3156	0.3198	0.3186	0.3538	0.3333	0.0000
1-	0.5679	0.5662	0.5596	0.5415	0.4375	0.0000
	1	2	3 Act	4 ual	5	6

# Dividing per $PM_{2.5}$ concentrations

	PM <sub>2.5</sub> <= 55.4 μg/m <sup>3</sup>		PM <sub>2.5</sub> > 55.4 μg/m <sup>3</sup>	
	Features	Accuracy	Features	Accuracy
Naïve Bayes	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub>	58.7%	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub>	91.7%
Random Forest	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub> , Iuminosity, noise level, microenvironment, and, GSM signal Strength	55.8%	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10,</sub> Iuminosity, noise level, microenvironment, and, GSM signal strength	92.6%
SVM	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub> , Iuminosity, noise level, microenvironment, and, GSM signal Strength	45.0%	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10,</sub> Iuminosity, noise level, microenvironment, and, GSM signal strength	91.6%

# Dividing per Microenvironment

	Indoor and Deep Indoor		Outdoor and Semi-outdoor	
	Features	Accuracy	Features	Accuracy
Naïve Bayes	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub>	82.9%	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub>	65.5%
Random Forest	PM2.5, PM1, PM10 luminosity, noise level, microenvironment, and, GSM signal strength	53.2%	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub> , luminosity, noise level, microenvironment, and, GSM signal strength	36.9%
SVM	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub> , Iuminosity, noise level, microenvironment, and, GSM signal strength	50.4%	PM <sub>2.5</sub> , PM <sub>1</sub> , PM <sub>10</sub> , Iuminosity, noise level, microenvironment, and, GSM signal Strength	35.6%



- Low-cost PM<sub>2.5</sub> sensors is suboptimal when compared to SidePak
- Collected data across contexts
- Classified data using three classification methods:
  - Naïve Bayes
    - The best classifier
    - Shows sensitivity towards contexts
  - Random Forest
    - Affected by the number of observation for each class
    - Not a very good classifier although it was used in recent works for calibration of other sensor [Zimmerman et al., 2018]
  - Support Vector Machine with Radial-Based Function kernel
    - Based on the number of observation for each class
    - The weakest classifier
- Next: improve the model by collecting data in more contextual conditions

# Human Interference





# Human Interference

- Everyday activities affect the concentrations of  $PM_{2.5}$  in the personal cloud
- Skin and Textile emissions affect the concentration of  $PM_{2.5}$  around the human body
- Interactions such as holding the sensor in hands affect the quality of sensor readings
- Physical characteristics of the PM<sub>2.5</sub> in personal cloud vary per source
- $PM_{2.5}$  varies in toxicity of PM based on its source

# Objectives



Identifying types of Human Interference that affect PM<sub>2.5</sub> sensors



Creating design guidelines for pollution-assessing wearables



- Used 2 prototypes of the wearable with high-precision PM<sub>2.5</sub> monitoring tool: SidePak
- Collected data for different human interference situations
- Analyzed data to identify human interference with PM<sub>2.5</sub> sensors

# Data Collection

- Two sensors
  - **Reference sensor** set at a fixed distance from the experiment
    - Distances: 30 cm and 100 cm
    - Some human interference situation has a larger radius of effect
  - Experiment Sensor
- Pollutants: PM<sub>1</sub>, PM<sub>2.5</sub>, PM<sub>10</sub>, and noise measured in dBA
- Contextual data collected by smartphone app



# Experiments

Group	Experimen	ts				
Control	Baseline C	ontrol				
Breath Group	Normal Bre	eathing	Laugh	Yawn	Cough	
Textile	Cotton	Fur	Leather	Wool	Synthetic	Silk
Skin Group	Skin no inte	erference	Skin sweating	Skin touching	Bracelets	Skin scratch
Hair Group	Hair touchi	ng		Hair heat style	;	
Toiletries	Face spray	Hair spray	Powder make	up	Spray perfum	е

# -

#### Between Experiment **Groups** and Baseline

# Analysis



Between **Experiments** and Baseline



Within experiment: between experimental sensor and reference sensor

### Control

#### Measuring pollutants without interference

#### SidePak and Wearable

#### Sensors are on a clean flat surface



# Breath Group

- The effect of breath on  $\mathsf{PM}_{2.5}$  values in the personal cloud
- 4 breath situations
  - Normal breathing
  - Yawning
  - Coughing
  - Laughing
- SidePak and Wearable
- Sensor clipped on a collar doing lightweight activities





# Hair Group

- Measuring hair emissions
- Two situations
  - Touching and playing with hair
  - Heat styling
- Sensor clipped on collar





# Skin Group

- Measured skin emissions
  - Near bare skin with no interference
  - Touching skin
  - Scratching skin
  - Wearing bracelets
  - Sweaty skin with no interference
- SidePak and Wearable
- Sensor was worn like a wristwatch with no interference with the outfit doing lightweight activity





# Toiletries

- Measuring use of toiletries as a day-today activity
  - Spraying perfume
  - Facial spray
  - Hair spray
  - Loose-powder makeup
- SidePak and Wearable
- Sensor clipped to the collar

Type Tool	Control
SidePak	Х
Wearable Sensor	$\checkmark$



# Textiles

- Measuring textile emissions
- 6 types of textile:
  - Cotton
  - Leather
  - Silk
  - Synthetic fabrics
  - Wool
  - Fur
- Sensor clipped on shirt pocket (or approximate location) doing lightweight activity

![](_page_42_Figure_11.jpeg)

### Human Interference and Baseline Comparison

Experiment	SidePak	Wearable
Cough	$\checkmark$	$\checkmark$
Hair touching	NA	$\checkmark$
Skin touching	$\checkmark$	$\checkmark$
Leather	NA	$\checkmark$
Face spray	X	X

### Human Interference and Distance

Experiment	@ 30 cm	@ 100 cm
Cough	X	Х
Hair touching	$\checkmark$	$\checkmark$
Skin touching	$\checkmark$	$\checkmark$
Wool	X	$\checkmark$
Powder makeup	X	$\checkmark$

![](_page_45_Picture_0.jpeg)

- PM<sub>2.5</sub> concentrations are affected by human interference
- Human PM differ to industrial PM in physical characteristics
- SidePak and two replicas of our wearable: experiment and reference at two distances 30 cm and 100 cm
- Experiments: control, breath, hair, skin, toiletries, and textile

More emiss	sions	Human Interference	Design practice
		Skin emissions	Minimize contact with skin
		Hair emissions then	Care for head area
		Breath emissions	Care for head area
		Textile (effect up to 30 cm distance)	Make account for textile emissions

Less emissions

### Contributions to HCI

**Identified** a set of **human interference situations** that affect pollution monitoring wearables

Inferred a set of basic **design guidelines** for personal pollution monitoring wearables

A **framework** for studying human interference with low-cost sensors

- Study different types of PM<sub>2.5</sub> sensors
- Study sensors that measure other types of pollutants

# Questions?

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### Image Credits

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